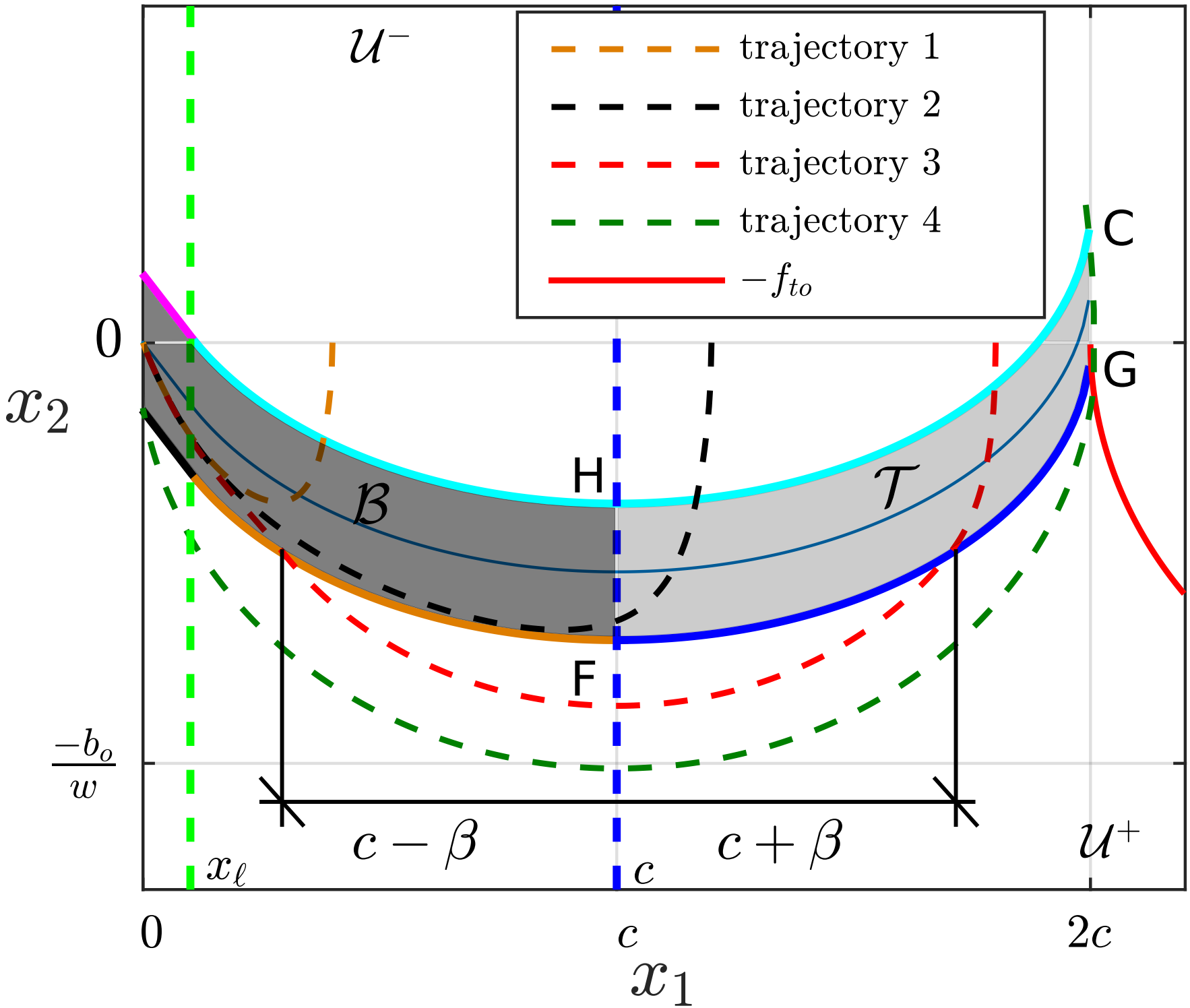
$\mathcal{U}^-$
trajectory 1
trajectory 2
trajectory 3
trajectory 4
$-f_{to}$
C
G
H
F
$\mathcal{B}$
$\mathcal{T}$
0
x_2
$\frac{-b_o}{w}$
$c-\beta$
$c+\beta$
x_ℓ
c
$\mathcal{U}^+$
0
c
$2c$
x_1